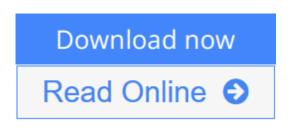


### Mechanisms and Machines: Kinematics, Dynamics, and Synthesis, SI Edition

By Michael M. Stanisic



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"The approach of using synthesis to motivate the study of analysis is meritorious. The vector loop and kinematic coefficient theory that is utilized throughout is modern and well suited to software implementation. This appeals to me as a user of such a text."

#### About the Author

Michael M. Stanisic earned the B.S.M.E., M.S.M.E. and Ph.D. degrees from Purdue University. Since 1988, he has been teaching and researching machine and manipulator design at the University of Notre Dame. He holds several patents on dextrous and singularity-free manipulator designs, which were developed with support from the National Science Foundation. He has published a number of papers concerning the application of Curvature Theory to the synthesis of mechanisms and to the control of robotic manipulators. In collaboration with the J. Stefan Institute, he has developed new types of humanoid shoulder mechanisms that include effects of human scapular motion. He has served several terms on the Mechanisms Committee of the American Society of Mechanical Engineers and has been a member of the International Scientific Committee for Advances in Robot Kinematics since 1988. At the University of Notre Dame, he has received numerous teaching awards at the departmental, college and university-wide levels.

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